



Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich



D-BSSE
Department of Biosystems
Science and Engineering

Getting started with ImarisXT and IcelmarisConnector

Extract from ImarisOPEN Launch

Belfast, 09.04.2013

```
function myFancyXTension(aImarisApplicationID)
% myFancyXTension is the next great XT function
% ...

% Set up connection between Imaris and MATLAB
conn = IcelmarisConnector(aImarisApplicationID);

% Get the currently selected Spots object in the scene
spots = conn.getSurpassSelection('Spots');
if isempty(spots)
    errordlg('Please select a Spots object.');
    return;
end

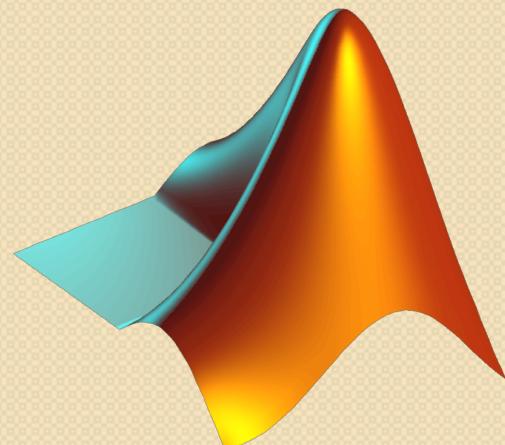
% Get all Surfaces objects in the scene
surfaces = conn.getAllSurpassChildren(0, 'Surfaces');
if isempty(surfaces)
    errordlg('There are no Surfaces objects in the scene.');
    return;
end

% Get the data volume in row-major order
data = conn.getDataVolumeRM(0, 0);
```

IcelmarisConnector is a simple commodity class that eases communication between Imaris and MATLAB using the ImarisXT interface.

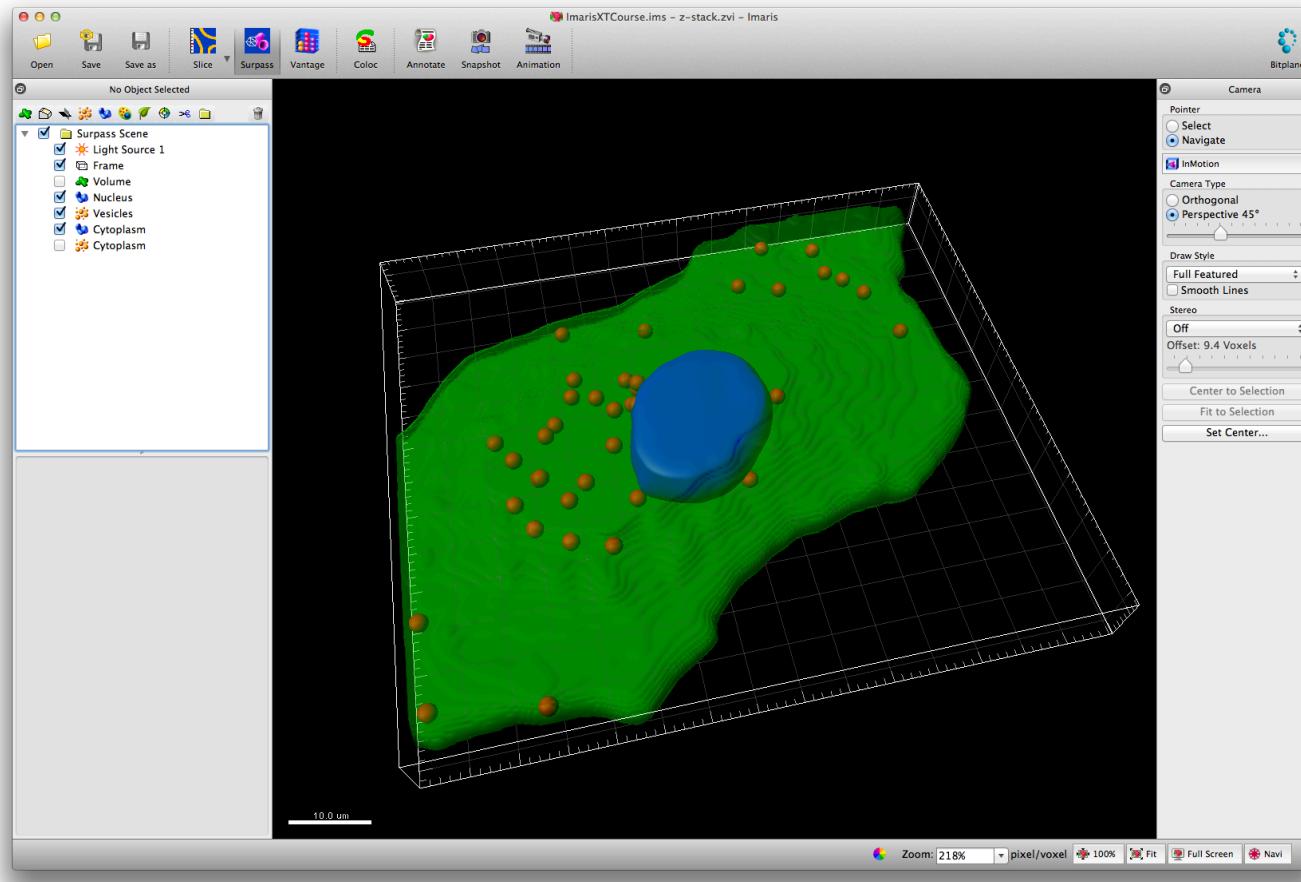
PART II

IcelmarisConnector

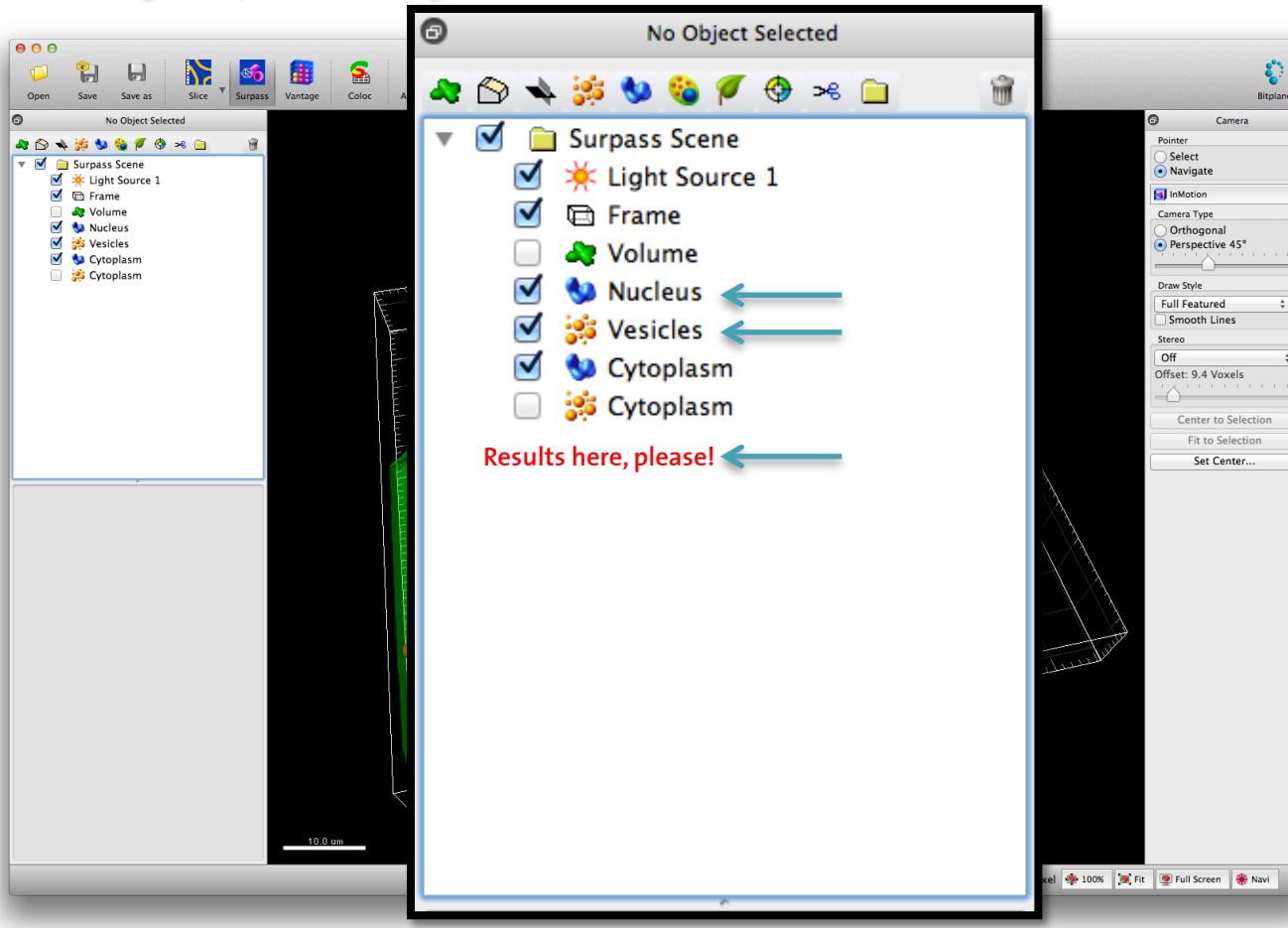


<http://www.scs2.net/next/index.php?id=110>

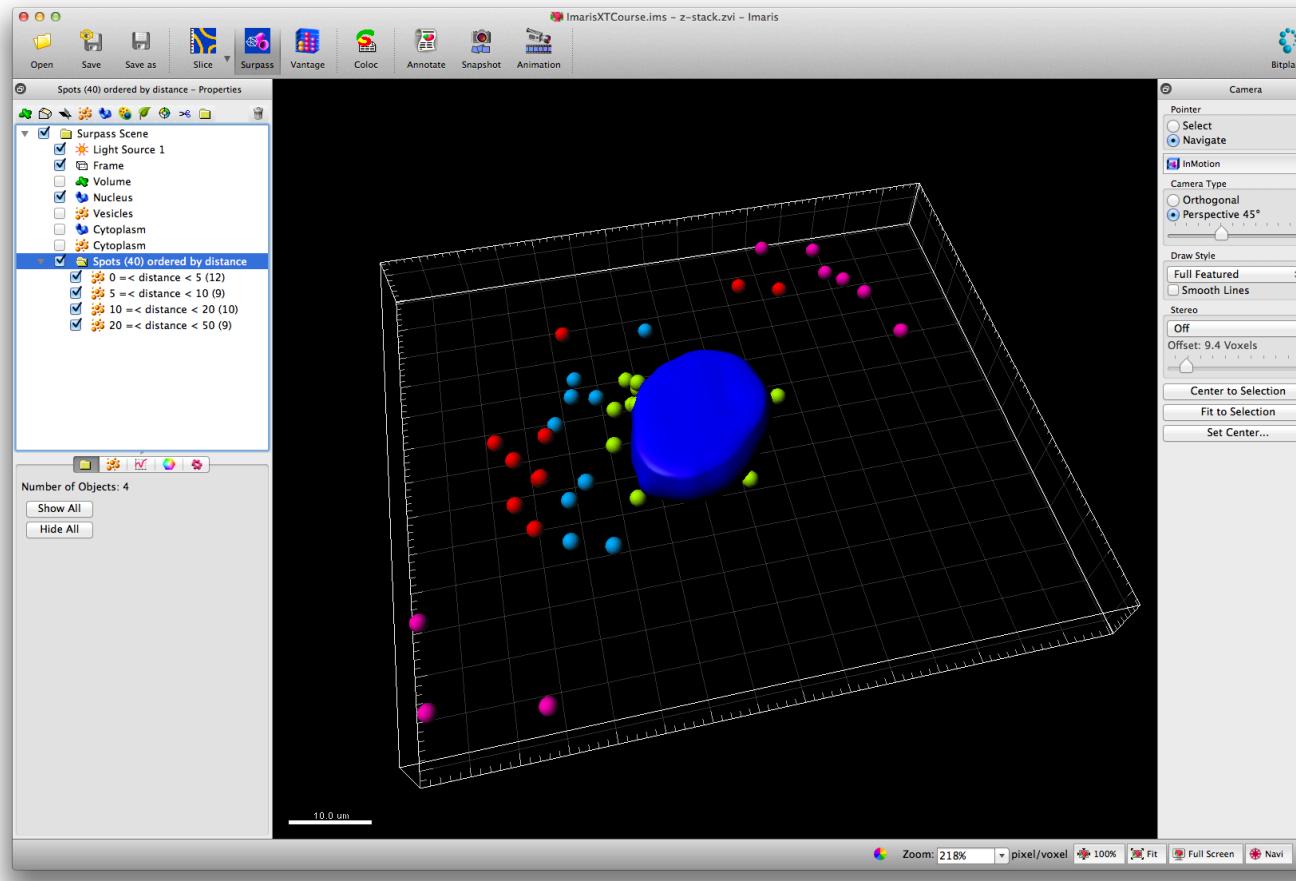
Getting started with ImarisXT / IcelmarisConnector Classify Spots by their distances from a Surface



Getting started with ImarisXT / IcelmarisConnector Classify Spots by their distances from a Surface



Getting started with ImarisXT / IcelmarisConnector Classify Spots by their distances from a Surface



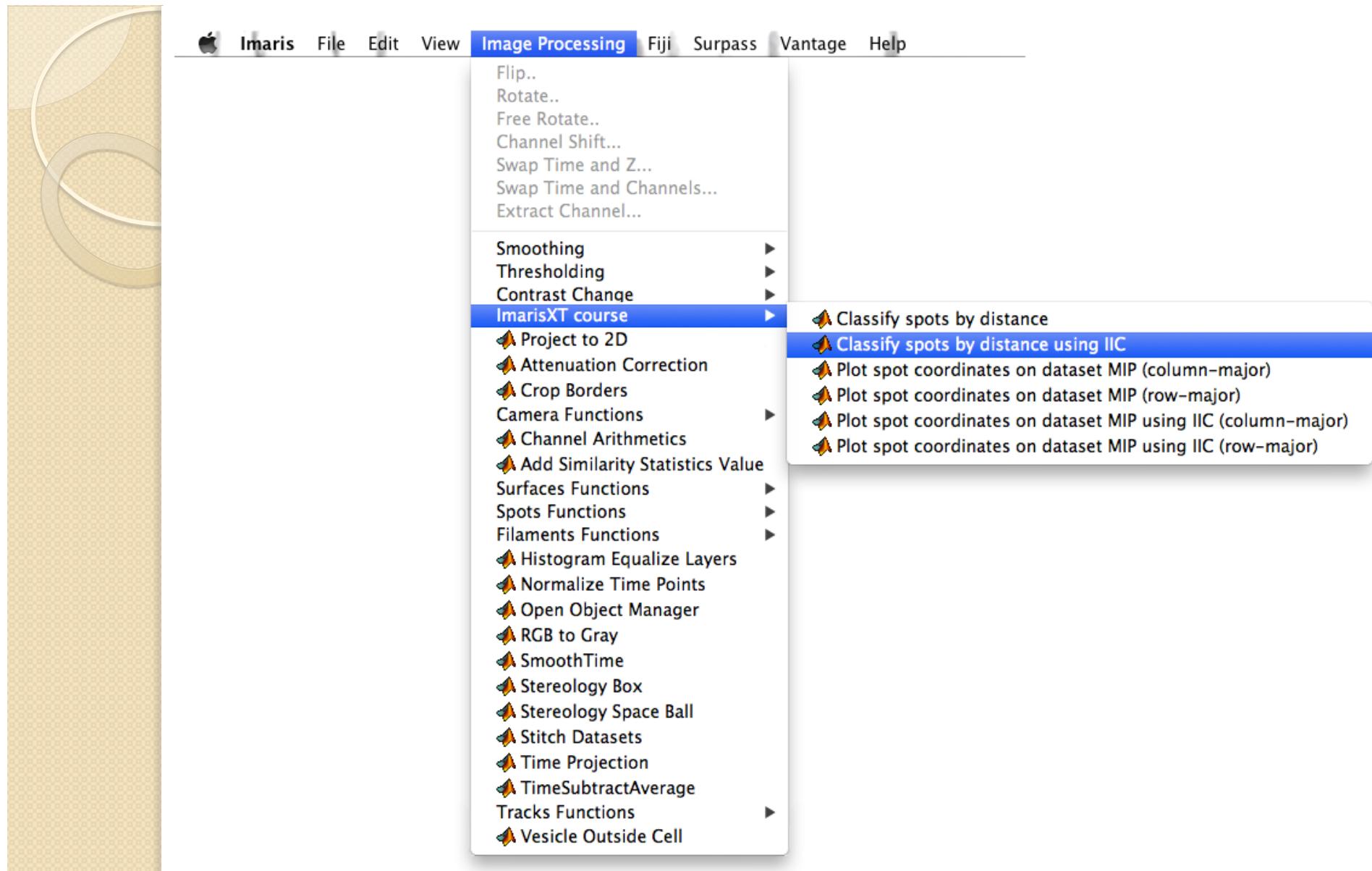
File: spotClassifyByDistanceIIC.m

```
function spotClassifyByDistanceIIC(aImarisApplicationID)
% Classifies the Spots by distance from the center of a surface using IceImarisConnector
%
% The distance limits are specified by the user via input dialogs.
% The classified spots are copied to new Spots objects.
%
% <CustomTools>
%   <Menu>
%     <Submenu name="ImarisXT course">
%       <Item name="Classify spots by distance using IIC" icon="Matlab">
%         <Command>MatlabXT::spotClassifyByDistanceIIC(%i)</Command>
%       </Item>
%     </Submenu>
%   </Menu>
%   <SurpassTab>
%     <SurpassComponent name="bpSpots">
%       <Item name="Classify spots by distance using IIC" icon="Matlab">
%         <Command>MatlabXT::spotClassifyByDistanceIIC(%i)</Command>
%       </Item>
%     </SurpassComponent>
%   </SurpassTab>
% </CustomTools>
%
% Copyright (c) 2012 - 2013, Aaron Ponti
```

The Imaris Application ID



The Imaris Application ID is an identifier that Imaris passes to MATLAB so that communication (via the Ice server) is possible.





File: spotClassifyByDistanceIIC.m / continued

```
% Set up connection between Imaris and MATLAB
conn = IceImarisConnector(aImarisApplicationID);

% Get the currently selected object in the surpass scene
vSpots = conn.getSurpassSelection('Spots');
if isempty(vSpots)
    errordlg('Please select a Spots object!');
    return
end

% Get the Surfaces objects
surfaces = conn.getAllSurpassChildren(false, 'Surfaces');
nSurfaces = numel(surfaces);
if nSurfaces == 0
    errordlg('There are no Surfaces in the scene!');
    return
end
if nSurfaces > 1
    % Ask the user to pick one surface
    vSurface = askUserToPickSurface(surfaces);
    if isempty(vSurface)
        return
    end
else
    vSurface = surfaces{ 1 };
end

% Get the center of mass of the Surfaces object
centerOfMass = vSurface.GetCenterOfMass(0);
```

Simplification...



File: spotClassifyByDistanceIIC.m / continued

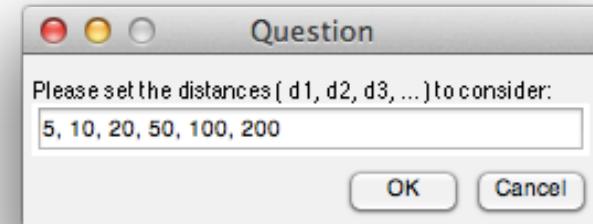
```
% Ask the user to specify the distance limits to use
distanceLimits = askUserToSetDistanceLimits();
if isempty(distanceLimits)
    return
end

% Get the spot coordinates, radii and time indices
spotValues = vSpots.Get();
coords = spotValues.mPositionsXYZ;
radii = spotValues.mRadii;
timeIndices = spotValues.mIndicesT;

% Calculate all spot distances from the center of mass
D = sqrt((coords(:, 1) - centerOfMass(1)).^2 + ...
          (coords(:, 2) - centerOfMass(2)).^2 + ...
          (coords(:, 3) - centerOfMass(3)).^2);

% Now classify all spots distances and create new Spots objects for each distance bin
for i = 2 : numel(distanceLimits)
    indx = find(D >= distanceLimits(i - 1) & D < distanceLimits(i));
    if ~isempty(indx)
        name = ['Spots ', num2str(distanceLimits(i - 1)), ...
                  '<= D < ', num2str(distanceLimits(i)), ' [', ...
                  num2str(numel(indx)), ']'];
        conn.createAndSetSpots(coords(indx, :), timeIndices(indx), ...
                               radii(indx), name, [rand(1, 3) 0]);
    end
end
```

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IcelmarisConnector

```
% Set up connection between Imaris and MATLAB  
conn = IceImarisConnector(aImarisApplicationID);
```

aImarisApplicationID can be:

- nothing
- an Imaris Application ID (*usually from Imaris*)
- an IcelmarisConnector reference (*conn*)
- an Imaris Application (ICE) instance.

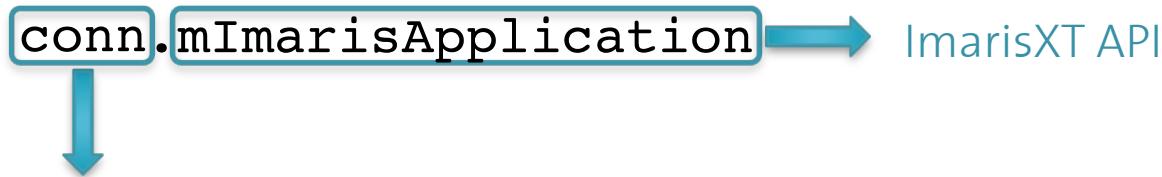
Vanilla ImarisXT

```
% Set up connection between Imaris and MATLAB  
if isa(aImarisApplicationID, 'Imaris.IApplicationPrxHelper')  
    vImarisApplication = aImarisApplicationID;  
else  
    % connect to Imaris interface  
    javaaddpath ImarisLib.jar  
    vImarisLib = ImarisLib;  
    if ischar(aImarisApplicationID)  
        aImarisApplicationID = round(str2double(aImarisApplicationID));  
    end  
    vImarisApplication = vImarisLib.GetApplication(aImarisApplicationID);  
end
```

The vImarisApplication object gives you access to the full ImarisXT API.

IcelmarisConnector – Imaris XT: a synergy

```
vImarisApplication = vImarisLib.GetApplication(aImarisApplicationID);
```



IcelmarisConnector API

ImarisXT API

```
spots = conn.mImarisApplication.GetSurpassSelection();
```

IcelmarisConnector API

```
data = conn.getDataVolume(0, 0);
```

IcelmarisConnector

```
% Get the currently selected object in the surpass scene  
vSpots = conn.getSurpassSelection('Spots');
```

optional filter

All IcelmarisConnector methods returning objects take care of autocasting them for you!

Vanilla ImarisXT

```
% Get the currently selected object in the surpass scene  
vSpots = vImarisApplication.GetSurpassSelection();  
vSpots = vImarisApplication.GetFactory().ToSpots(vSpots);
```

The returned object must be explicitly cast to Spots!

IcelmarisConnector

```
% Get the Surfaces objects
surfaces = conn.getAllSurpassChildren(false, 'Surfaces');
```

(do not) recurse into folders optional filter

Vanilla ImarisXT

```
% Get the Surfaces objects (at the root level!)
surfaces = {}; nSurfaces = 0;
nChildren = vImarisApplication.GetSurpassScene().GetNumberOfChildren();
for i = 0 : (nChildren - 1)
    child = vImarisApplication.GetSurpassScene.GetChild( i );
    if vImarisApplication.GetFactory().IsSurfaces(child)
        nSurfaces = nSurfaces + 1;
        % We must cast the child to a Surfaces object!
        surfaces{nSurfaces} = ...
            vImarisApplication.GetFactory().ToSurfaces(child);
    end
end
```

You should turn this into a recursive function to scan all folders!

IcelmarisConnector

```
% Create and add a new Spots object  
conn.createAndSetSpots(coords, timeIndices, radii, name, [rand(1, 3) 0], container);
```

↑
transparency optional

Vanilla ImarisXT

```
% Create and add a new Spots object  
newSpots = vImarisApplication.GetFactory().CreateSpots();  
newSpots.Set(coords, timeIndices, radii);  
newSpotsSetColorRGBA(uint32(randi(255, [1 3]) * [1; 256; 256^2]));  
newSpotsSetName(name);  
vImarisApplication.GetSurpassScene().AddChild(newSpots, -1);
```

↑
Setting transparency is very tricky
with vanilla Imaris XT!



IcelmarisConnector

```
% Get the data volume for channel 0 and timepoint 0  
stack = conn.getDataVolume(0, 0)
```

This we haven't seen in the original example,
but it is interesting anyway.

Vanilla ImarisXT

```
% Get the iDataSet object
iDataSet = vImarisApplication.GetDataSet();

% Get the data type
switch char(iDataSet.GetType())
    case 'eTypeUInt8',   datatype = 'uint8';
    case 'eTypeUInt16',   datatype = 'uint16';
    case 'eTypeFloat',   datatype = 'single';
    otherwise,           error('Bad value for iDataSet.GetType()');
end

% Allocate memory
stack = zeros([iDataSet.GetSizeX(), iDataSet.GetSizeY(), iDataSet.GetSizeZ()], datatype);

% Get the pixel data
switch char(iDataSet.GetType())
    case 'eTypeUInt8',           huge speedup! 😎
        arr = iDataSet.GetDataVolumeAs1DByteArrays(0, 0);
        stack(:) = typecast(arr, 'uint8');
    case 'eTypeUInt16',
        arr = iDataSet.GetDataVolumeAs1DArrayShorts(0, 0);
        stack(:) = typecast(arr, 'uint16');
    case 'eTypeFloat',
        stack(:) = iDataSet.GetDataVolumeAs1DArrayFloats(0, 0);
    otherwise,
        error('Bad value for type');
end
```

IcelmarisConnector takes care of all memory allocations, getting data with the correct XT method and performing type casting as needed.

huge speedup! 😎



← typecast needed 😢

← typecast needed 😢

Great for debugging!



Starting Imaris from MATLAB

Command Window

```
>> conn = IceImarisConnector()
IceImarisConnector: not connected to an Imaris instance yet.
>> conn.startImaris()
ans =
    1
>> conn
IceImarisConnector: connected to Imaris.
>>
```

Starts Imaris and connects to it!

Switch to Imaris, load dataset, run spot detection, ...

f_x

Great for debugging!



Starting Imaris from MATLAB



```
Editor - /Users/aaron/Downloads/XTensions/spotClassifyByDistancellC.m
EDITOR PUBLISH VIEW
FILE EDIT NAVIGATE BREAKPOINTS RUN
+ New - Open Save Find Files Compare Insert Comment Go To Breakpoints Run
- Print Indent Find Run and Time Run and Advance Run Section Advance
spotClassifyByDistancellC.m
25
26 % Set up connection between Imaris and MATLAB
27 conn = IceImarisConnector(aImarisApplicationID);
28
29 % Get the currently selected object in the surpass scene
30 vSpots = conn.getSurpassSelection();
31 if isempty(vSpots)
32     errordlg('Please select a Spots object!');
33     return
34 end
35
36 % Get the Surfaces objects
37 surfaces = conn.getAllSurpassChildren(0, 'Surfaces');
38 nSurfaces = numel(surfaces);
39 if nSurfaces == 0
40     errordlg('There are no Surfaces in the scene!');
41     return
42 end
...instancellC / askUserToSetDistanceLimits | Ln 117 Col 21
```

Starting Imaris from MATLAB

Great for debugging!



```
Command Window
>> conn = IceImarisConnector()
IceImarisConnector: not connected to an Imaris instance yet.
>> conn.startImaris()
ans =
    1
>> conn
IceImarisConnector: connected to Imaris.
>>

Switch to Imaris, load dataset, run spot detection, ...

>> spotClassifyByDistanceIIC(conn)
fx >>
```

Now we can run/debug the XTension from the MATLAB console passing the IceImarisConnector instance as an argument.

```
>> spots = conn.getSurpassSelection('Spots');
```

When the XTension is finished, we can work interactively with the Imaris instance and the results of our XTension.